

In the Claims

Please replace the claims with the following re-written version:

1. – 32. (Cancelled)

33. (Currently Amended) Handling system for lifting and moving a person from a first position to another, said system comprising

a frame including a base frame and a lifting frame being part of a lifting device for said person,

at least three wheels positioned in different parts of said base frame and allowing the handling system to be moved over a surface from said first position to another, each of said wheels are mounted pivotally around a vertical axle of said wheels

at least one user interface allowing said person or another person to control the handling system,

at least one of said wheels is directional controllable by a controller from said at least one user interface from a first wheel position to a second wheel position, said controller being wire or wirelessly connected to said at least one user interface,

wherein

the angle of direction of said at least one wheel is respectively 0 and 90 degrees in relation to a forward direction of said handling system, with a direct change of wheel position from 0 to 90 degrees.

34. (Previously Presented) Handling system according to claim 33, wherein the angle of direction of said at least one wheel is exactly 0 and 90 degrees, respectively.

35. (Previously Presented) Handling system according to claim 33, wherein the direction of any of said wheels are directly controlled.

36. (New) Handling system according to claim 33, wherein some of said at least three wheels are directly controlled wheels and some are free directional wheels.

37. (Previously Presented) Handling system according to claim 36, wherein said free directional wheels are controlled by movement of said system.
38. (Previously Presented) Handling system according to claim 33, wherein said system comprises at least two free directional wheels and at least one directional controlled wheel .
39. (Previously Presented) Handling system according to claim 33, wherein the system is directionally controlled by at least one controller controlling the angle of direction of said directional controlled wheels.
40. (Previously Presented) Handling system according to claim 39, wherein said controller is connected to said directional controlled wheels by rods, electric actuators or similar connection arms.
41. (Previously Presented) Handling system according to claim 33, wherein at least one controller controls a width horizontally between right and left parts of the base frame by pivoting said parts around vertical axles for said parts.
42. (Previously Presented) Handling system according to claim 39, wherein said controllers are wire or wireless connected to said user interface.
43. (Previously Presented) Handling system according to claim 33, wherein said user interface includes control means comprising as computer means and storage means comprising predefined motor control data or ramps for controlling at least one electric motor.
44. (Previously Presented) Handling system according to claim 33, wherein said user interface includes communication means for communicating system or person data.
45. (Previously Presented) Handling system according to claim 33, wherein at least one electric motor is connected to at least one of said wheels.

46. (Currently Amended) User interface for a handling system according to claim 33 for lifting and/or moving a person from a first position to another,

said user interface comprises control means capable of converting the handling of said interface by said person or another person to directly or indirectly control of the direction of each of the wheels of said handling system by a controller, said controller being wire or wirelessly connected to said at least one user interface,

wherein

said interface controls the angle of direction of each of the wheels with a direct change of wheel position from 0 to 90 degrees in relation to a forward direction of said handling system by pivoting the wheels around a vertical axle of said wheels.

47. (Previously Presented) User interface according to claim 46, wherein said user interface further controls power directed to one or more of the wheels in response to the handling by said person or another person.

48. (Previously Presented) User interface according to claim 46, wherein a control device of said user interface includes at least one joystick or similar control stick.

49. (Previously Presented) User interface according to claim 48, wherein one or more buttons converts said control device from a status of substantially forward movement to a sideways movement by a direction of approximately 0 degrees or 90 degrees in relation to a forward direction of said handling system.

50. (Previously Presented) User interface according to claim 46, wherein said control means includes computer means and storage means comprising predefined motor control data or ramps.

51. (Previously Presented) User interface according to claim 46, wherein said control means includes communication means for communicating system or person data.

52. (Previously Presented) User interface according to claim 46, wherein said interface controls a controller to control the direction of said directional controlled wheels by pivoting the wheels around a vertical axle for said wheels and a controller to control a width horizontally between right and left parts of the base frame of said handling system by pivoting said parts around vertical axles of said parts.

53. (Currently Amended) Method of handling a person by lifting and moving the person from a first position to another, with a handling system including at least one user interface, said method comprising:

lifting the person by a lifting device of said handling system,
moving the person in said handling system, and
directly or indirectly controlling a direction of wheels of said handling system by said at least one user interface where a direction of at least one wheel is controlled by a controller with a direct change of wheel position from 0 to 90 degrees in relation to a forward direction of said handling system said controller being wire or wirelessly connected to said at least one user interface,

in which the control is performed by the person being handled or an assistant.

54. (Previously Presented) Method of handling a person according to claim 53, wherein said movement is achieved by powering one or more of the wheels of the system with one or more electric motors connected to said one or more wheels.

55. (Previously Presented) Method of handling a person according to claim 54, wherein a direction of said at least one wheel is exactly 0 and 90 degrees, respectively.

56. (Previously Presented) Method of handling a person according to claim 53, wherein the handling of said interface directly or indirectly controls a direction of each of the wheels of said handling system by pivoting the wheels around a vertical axle of said wheels.

57. (Previously Presented) Method of handling a person according to claim 54, wherein said handling controls the power directed to one or more of the electric motors connected to said wheels.

58. (Previously Presented) Method of handling a person according to claim 54, wherein said at least one electric motor controlled by a control device of said user interface including a control stick.

59. (Previously Presented) Method of handling a person according to claim 54, wherein said at least one electric motor is controlled by said user interface including computer means and storage means comprising predefined motor control data or ramps.

60. (Previously Presented) Method of handling a person according to claim 53, wherein at least one controller controls the direction of said directional controlled wheels.

61. (Previously Presented) Method of handling a person according to claim 60, wherein said controller controls said directional controlled wheels by rods, electric actuators or connection arms.

62. (Previously Presented) Method of handling a person according to claim 53, wherein at least one controller controls a width horizontally between right and left parts of the base frame of said handling system by pivoting said parts around vertical axles of said parts.